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# **A New Technique for Solving Poisson's Equation on Domains of Arbitrary Aspect Ratio**

Robert Ryne  
Lawrence Berkeley National Laboratory

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# Acknowledgements

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## ■ Work performed in collaboration with

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- R. Gluckstern, U. Maryland, retired

# Modeling systems with large aspect ratios is a difficult and important issue

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- Issue: Poisson solvers used in PIC codes often **fail when grid aspect ratio  $\gg 1$**
- Relevance: Many important problems involve extreme aspect ratios:
  - Long beams in rf circular accelerators: length  $\sim 1\text{m}$ ; radius  $\sim 1\text{mm}$
  - Flat beams (as at interaction point of lepton colliders)
  - Beams in induction linacs: length  $\sim 10\text{s of meters}$ ; radius  $\sim \text{cm}$
  - Galaxies
- Standard grid-based approaches use very large # of grid points in the long dimension, leading to **prohibitively long run times**
- As a result, it is extremely difficult or impossible to model high aspect ratio systems accurately using standard grid-based approaches, even on terascale computers

# A potential “brick wall” in the road to large-scale space-charge simulations of beams in circular machines

- mid-to-late 1990s : parallel high current linac modeling codes
    - Example: IMPACT code
    - linac length ~km; ~1000s steps (Poisson solves); ellipsoidal bunches
  - Early 2000s:
    - Parallel weak-strong and strong-strong beam-beam simulations in colliders
    - Major advances including first-ever million-particle, million-turn strong-strong beam-beam simulation (J. Qiang)
  - 2000+ : advance to modeling beams with space charge in circular machines
    - Very long simulations: 1000's to millions of turns
    - More difficult Poisson problem if aspect ratio is large
    - Keeping grid near-square would involve ~10-1000x more grid points
- (>1000s more steps) x (10-1000x more grid points) □  
 *$10^4$  to  $>10^6$  times more challenging than linac modeling*
  - Will not get this advance from hardware alone; also need advances in algorithms

# Poisson Problem: Observation

- The Green function,  $G$ , and source density,  $\rho$ , may change over vastly different scales
- In simple geometries  $G$  is known apriori;  $\rho$  is not

We should use our full knowledge of  $G$ , as needed, to obtain accurate, efficient, and robust solution of the Poisson problem

- Example: 2D Poisson equation in free space

$$\phi(x, y) = \iint G(x - x', y - y') \rho(x', y') dx' dy'$$

$$G(x - x', y - y') = \frac{1}{2} \ln((x - x')^2 + (y - y')^2)$$

# Standard Approach (Hockney and Eastwood)

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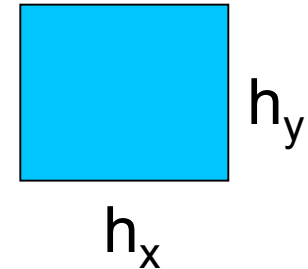
$$\phi(x, y) = \iiint G(x - x', y - y') \phi(x', y') dx' dy'$$

$$\phi_{i,j} = \sum G_{i-i', j-j'} \phi_{i',j'} \quad G_{0,0} = G_{0,1}$$

- approach makes use of only **partial knowledge of G**
- equivalent to trapezoidal rule to approximate the convolution integral
- Cutoff at  $(x,y)=(0,0)$ ; isotropy issue for large aspect ratio
- error depends on how rapidly the integrand,  $\phi G$ , varies over an elemental cell
  - If  $\phi$  changes slowly we might try to use a large grid spacing; but this can introduce huge errors due to the change in G over a cell length

# Cellular Analytic Convolution (CAC)

- Assume  $\phi$  varies in a prescribed way in each cell
- Use analytic Green function to perform the convolution integral exactly in each cell, then sum over cells
- Example: linear basis functions to approximate  $\phi$ .



$$\begin{aligned} \phi(x_i, y_j) = & \frac{1}{h_x h_y} \sum_{i', j'} \phi_{i', j'} \int_0^{h_x} dx' \int_0^{h_y} dy' (h_x - x')(h_y - y') G(x_i - x_i' - x', y_j - y_j' - y') + \\ & \frac{1}{h_x h_y} \sum_{i', j'} \phi_{i+1, j'} \int_0^{h_x} dx' \int_0^{h_y} dy' x' (h_y - y') G(x_i - x_i' - x', y_j - y_j' - y') + \\ & \frac{1}{h_x h_y} \sum_{i', j'} \phi_{i, j+1} \int_0^{h_x} dx' \int_0^{h_y} dy' (h_x - x') y' G(x_i - x_i' - x', y_j - y_j' - y') + \\ & \frac{1}{h_x h_y} \sum_{i', j'} \phi_{i+1, j+1} \int_0^{h_x} dx' \int_0^{h_y} dy' x' y' G(x_i - x_i' - x', y_j - y_j' - y') \end{aligned}$$

- Shifting the indices results in a single convolution\*  $\phi_{i, j} = \sum_{i', j'} G_{i-i', j-j'}^{eff} \phi_{i', j'}$  involving an integrated effective Green function:

# $G^{\text{eff}}$ consists of 4 terms: what are they?

- 1st term: Indefinite integral is function of  $(x_i - x_j, y_i - y_j) = (a, b)$  evaluated at  $(a, b)$ ,  $(a - h_x, b)$ ,  $(a, b - h_y)$ ,  $(a - h_x, b - h_y)$

$$\begin{aligned}
 & -\frac{x^3}{9} - \frac{1}{4} (hx - s) x^2 + \\
 & \frac{1}{12} (-3s + 3hx + 2x) \log(x^2 + y^2) x^2 + \\
 & \frac{1}{6} y (-3b + 3hy + 2y) x - \\
 & \frac{1}{2} (b - hy) (-2s + 2hx + x) \tan^{-1}\left(\frac{y}{x}\right) x - \\
 & \frac{1}{6} (2y^3 - 3by^2 + 3hy y^2) \tan^{-1}\left(\frac{x}{y}\right) - \\
 & \frac{1}{4} (s y^2 - hx y^2 - 2s b y + 2b hx y + 2s hy y - 2hx hy y) \\
 & \log(x^2 + y^2)
 \end{aligned}$$



# No interaction cutoff at short distances

- Formulas look like they have singularities, but result must be finite
- In general, limiting form is needed in 4 cases:
  - $(x_i - x_j \rightarrow 0, y_j - y_j \rightarrow 0), (x_i - x_j \rightarrow h_x, y_j - y_j \rightarrow 0), (x_i - x_j \rightarrow 0, y_j - y_j \rightarrow h_y), (x_i - x_j \rightarrow h_x, y_j - y_j \rightarrow h_y)$
- Example:  $(x_i - x_j \rightarrow h_x, y_j - y_j \rightarrow h_y)$

$$\begin{aligned} & \frac{1}{6} \left( -16 h_y^3 \operatorname{ArcTan} \left[ \frac{h_x}{2 h_y} \right] + 12 h_y^3 \operatorname{ArcTan} \left[ \frac{h_x}{h_y} \right] - \right. \\ & \quad 2 h_y^3 \operatorname{ArcTan} \left[ \frac{2 h_x}{h_y} \right] - 24 h_x^2 h_y \operatorname{ArcTan} \left[ \frac{h_y}{2 h_x} \right] + \\ & \quad 36 h_x^2 h_y \operatorname{ArcTan} \left[ \frac{h_y}{h_x} \right] - 12 h_x^2 h_y \operatorname{ArcTan} \left[ \frac{2 h_y}{h_x} \right] + \\ & \quad h_x^3 \operatorname{Log} [h_x^2] - 4 h_x^3 \operatorname{Log} [4 h_x^2] - \\ & \quad 2 h_x^3 \operatorname{Log} [h_x^2 + h_y^2] + 6 h_x h_y^2 \operatorname{Log} [h_x^2 + h_y^2] + \\ & \quad 8 h_x^3 \operatorname{Log} [4 h_x^2 + h_y^2] - 6 h_x h_y^2 \operatorname{Log} [4 h_x^2 + h_y^2] + \\ & \quad h_x^3 \operatorname{Log} [h_x^2 + 4 h_y^2] - 12 h_x h_y^2 \operatorname{Log} [h_x^2 + 4 h_y^2] - \\ & \quad \left. 4 h_x^3 \operatorname{Log} [4 h_x^2 + 4 h_y^2] + 12 h_x h_y^2 \operatorname{Log} [4 h_x^2 + 4 h_y^2] \right) \end{aligned}$$

# Cost and Accuracy; Improvement over Hockney Approach

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- Cost: Computing the elemental integrals can be done via analytical formulae or by numerical quadrature
  - Requires more FLOPS than simply using  $G_{ij}$  but...
  - when the grid is fixed, needs to be done once at the start of a run. Amortized over many time steps, does not significantly impact run time.
  - Note well: sensitivity to roundoff for large aspect ratios. Care required!
- Accuracy: Method works well as long as the elemental integrals are computed accurately and as long as the grid and # of macroparticles are sufficient to resolve variation in  $\square$ 
  - maintains accuracy even for extreme aspect ratios (>1000:1)

*As a result, new method performs orders of magnitude better than the standard convolution algorithm for realistic problems involving large aspect ratios*

# Example: Uniformly filled 2D ellipse

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- **Aspect ratio is 1:1000**

- $x_{\max}=0.001$ ,  $y_{\max}=1$

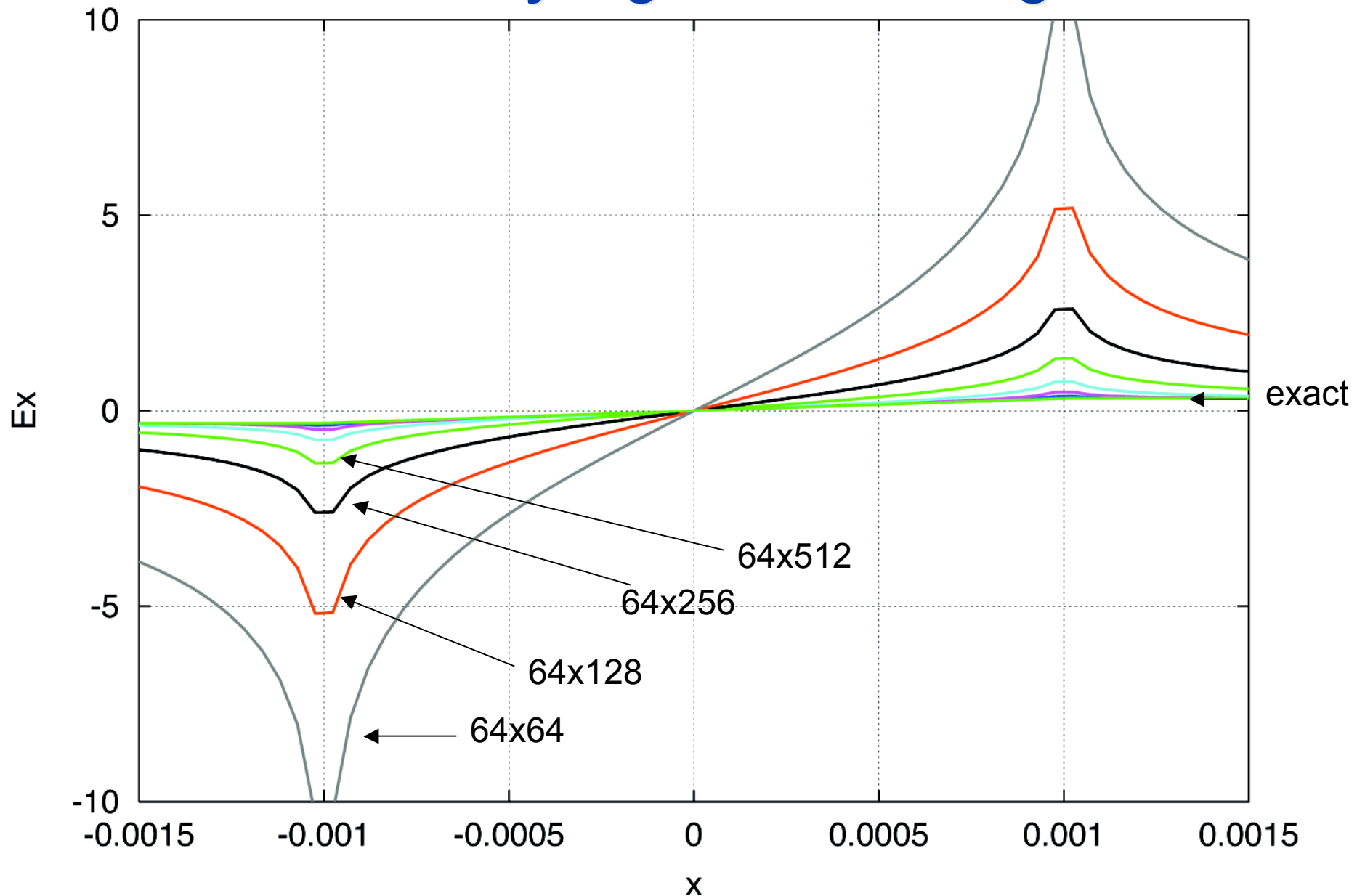
- **Calculation of fields using (1) standard Hockney algorithm and (2) new approach**

- In both cases, performed convolutions for the fields directly (rather than calculating the potential and using finite differences to obtain fields)

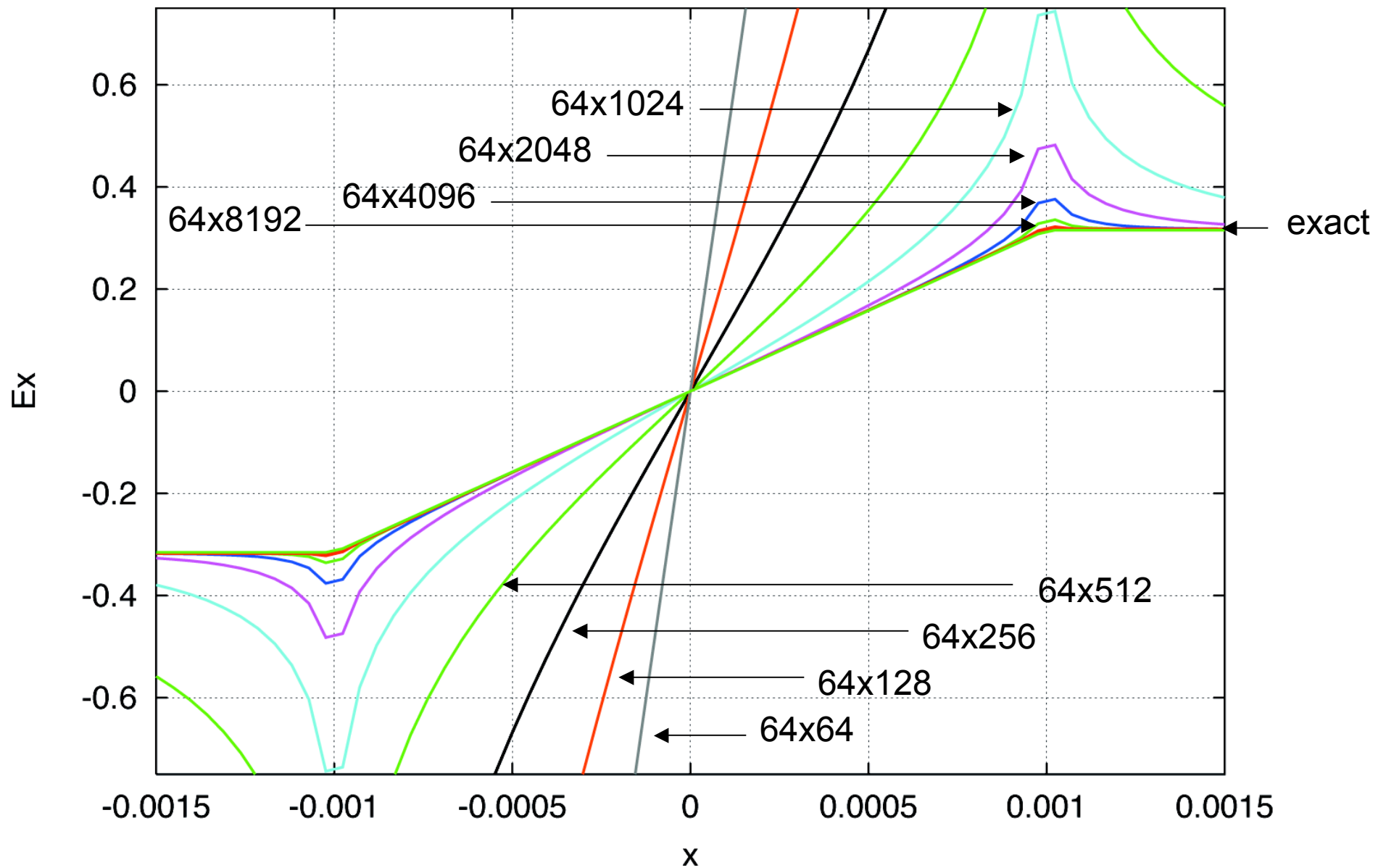
- **Calculation performed on a grid of size  $\pm 0.0015 \times \pm 1.5$  using a mesh of size**

- Hockney: 64x64, 64x128, 64x256,..., 64x16384
- New approach: 64x64

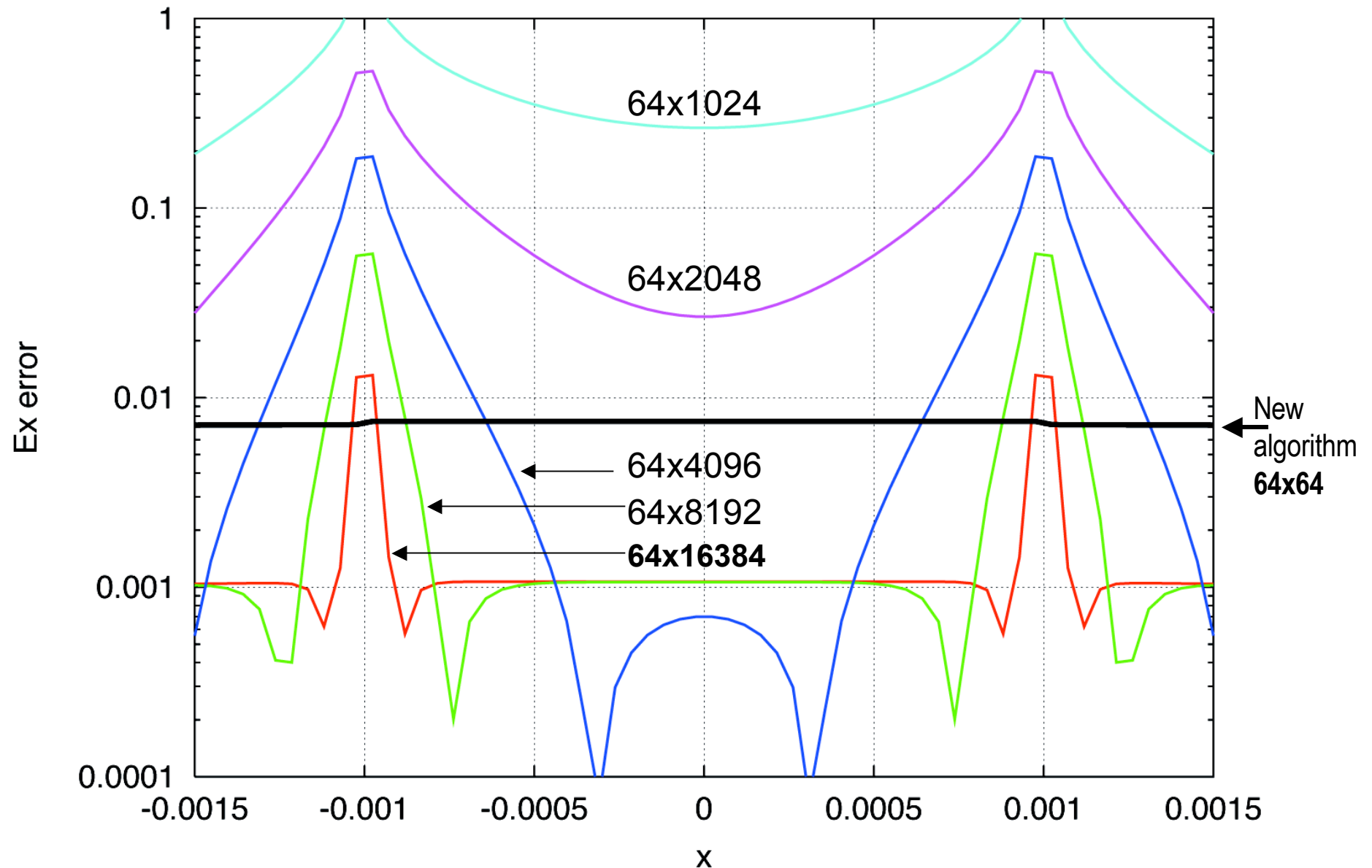
# 1:1000 test case; $E_x$ vs. $x$ : Standard Hockney Algorithm has huge errors



# Ex vs. x : Reduced Vertical Scale



Old algorithm has large errors until grid size reaches ~ **64x8192**.  
New algorithm has excellent accuracy on a grid as small as **64x64**



# Comparisons with other methods

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## ■ Comparison with the finite element method:

- New method uses basis functions, but there is no variational quantity to be numerically minimized and no linear system to be solved
  - This is done analytically

## ■ Comparison with the finite difference method:

- FD approximates: (1) continuous operators by stencils on grids, and (2) sources by values at grid points
  - Error in (1) depends on behavior of the solution,  $\phi$ , compared with the FD approximation to  $\phi^2$
- Error in new approach is *source-limited*, i.e. it only depends on the deviation of the source,  $\psi$ , from the assumed functional form
  - No issue with anisotropy except indirectly through the representation of  $\psi$

# Comment on Direct Convolution Methods

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- Would not be generally useful except for the key fact that *a discrete convolution can be turned into a cyclic convolution through zero padding and periodization of  $G$* 
  - Turns  $N^2$  method into  $N \log N$  at the price of grid doubling\*
  - Works when  $G=G(x-x')$
  - Also works when  $G=G(x+x')$



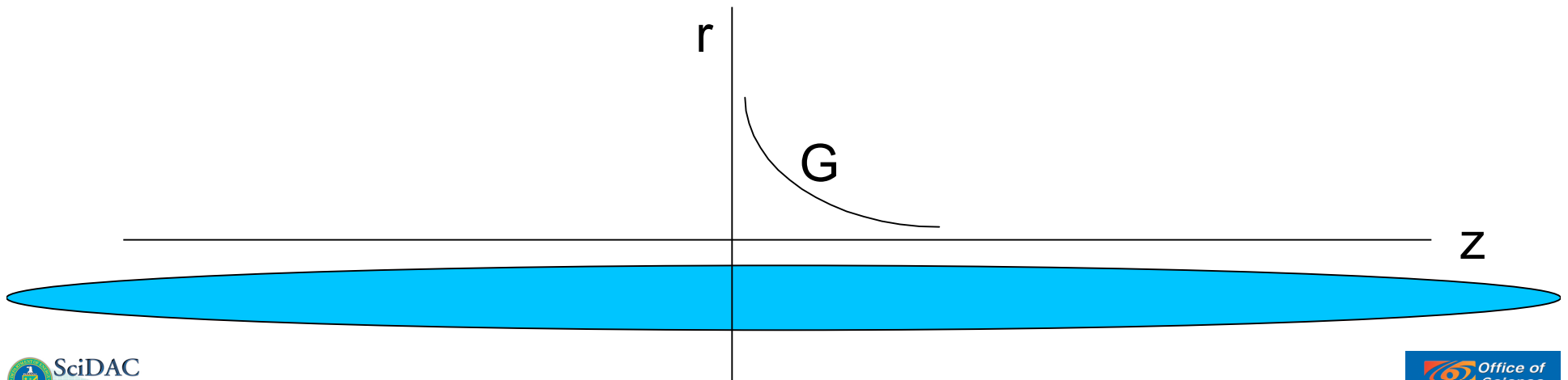
# Future Directions

## ■ Extension to 3D straightforward but messy

- Formulas have been generated using a symbolic math program
- Implementation underway

## ■ Question: Can this general approach (i.e. using full analytical knowledge of $G$ ) be used in other simple geometries?

- Can do Dirichlet in a box (write  $G$  as sum of convolutions/correlations)
- Long beams in pipes:
  - Analytic approach to integration is crucial since  $G$  and  $\kappa$  may vary on vastly different scales
  - potential performance increase by making use of shielding (exponential falloff) in the long direction to discard terms beyond a certain distance from the source



# Extension to Beams in Pipes

- CAC provides a crucial advantage, since the Green function falls off exponentially in  $z$ , though  $\square(z)$  may change slowly over meters
- Due to shielding, sum can be truncated in the “long” direction:

$$\square_{i,j} = \sum_{i'=1}^{N_x} \sum_{j'=j-j_{cutoff}}^{j+j_{cutoff}} G_{i \square i', j \square j'}^{eff} \square_{i',j'}$$

- For long beam in a conducting pipe, if grid length in  $z$  is  $\gg$  pipe radius, can truncate at nearest neighbors:

$$\square_{i,j} = \sum_{i'=1}^{N_x} (G_{i \square i', j \square j-1}^{eff} \square_{i',j-1} + G_{i \square i', j}^{eff} \square_{i',j} + G_{i \square i', j+1}^{eff} \square_{i',j+1})$$

- For a rectangular pipe, can rewrite Green function as a sum of convolutions and correlations; then can still use FFT-based approach to sum over elements